# Towards Symbolic Factual Change in Dynamic Epistemic Logic 

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Are there more red or more blue points?


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Representation matters!

## 1. Dynamic Epistemic Logic

2. Symbolic Model Checking
3. Factual Change

## Epistemic Logic

## Syntax

$$
\varphi::=p|\neg \varphi| \varphi \wedge \varphi \mid K_{i} \varphi
$$

## Kripke Models

$\mathcal{M}=\left(W, R_{i}\right.$, Val $)$ where

- W set of worlds
- $R_{i} \subseteq W \times W \quad$ indistinguishability relation
- Val : $W \rightarrow \mathcal{P}(P)$ valuation function


## Semantics

$\mathcal{M}, w \models K_{i} \varphi$ iff $w R_{i} v$ implies $\mathcal{M}, v \models \varphi$

## Dynamic Epistemic Logic: Action Models

## Action Models

$\mathcal{A}=(A, R$, pre, post $)$ where

- A
- $R_{i} \subseteq A \times A$
- pre : $A \rightarrow \mathcal{L}$
- post : $A \rightarrow P \rightarrow \mathcal{L}$
set of atomic events indistinguishability relation precondition function
postcondition function


## Product Update

$\mathcal{M} \times \mathcal{A}:=\left(W^{\text {new }}, \mathcal{R}_{i}^{\text {new }}, V\right.$ Val $\left.{ }^{\text {new }}\right)$ where

- $W^{\text {new }}:=\{(w, a) \in W \times A \mid \mathcal{M}, w \vDash \operatorname{pre}(a)\}$
- $\mathcal{R}_{i}^{\text {new }}:=\left\{((w, a),(v, b)) \mid \mathcal{R}_{i} w v\right.$ and $\left.R_{i} a b\right\}$
- $\operatorname{Val}^{\text {new }}((w, a)):=\left\{p \in V \mid \mathcal{M}, w \vDash \operatorname{post}_{a}(p)\right\}$
(Baltag, Moss, and Solecki 1998,Benthem, Eijck, and Kooi (2006))

DEL Example: Coin Flip hidden from a


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## Model Checking - The Task

Given a model and a formula, does it hold in the model?

$$
\mathcal{M}, w \models \varphi \quad \text { or } \mathcal{M}, w \not \models \varphi
$$

???

## Limits of Explicit Model Checking

Set of possible worlds has to fit in memory. For large models ( $\sim 1000$ worlds) this gets slow. Runtime in seconds for $n$ Muddy Children:

| n | DEMO-S5 |
| :---: | ---: |
| 6 | 0.012 |
| 8 | 0.273 |
| 10 | 8.424 |
| 11 | 46.530 |
| 12 | 228.055 |

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## Symbolic Model Checking



- Can we represent models in a more compact way? ... such that we can still interpret all formulas?


## Symbolic Model Checking



- Can we represent models in a more compact way?
... such that we can still interpret all formulas?
Yes!

1. Represent $\mathcal{M}=\left(W, R_{i}\right.$, Val $)$ symbolically: $\mathcal{F}=\left(V, \theta, O_{i}\right)$.
2. Translate DEL to equivalent boolean formulas.
3. Use Binary Decision Diagrams to speed it up.

## Knowledge Structures

## Knowledge Structures

$\mathcal{F}=\left(V, \theta, O_{1}, \cdots, O_{n}\right)$ where

- Vocabulary set of propositional variables
- $\theta$ State Law boolean formula over $V$
- $O_{i} \subseteq V \quad$ Observables propositions observable by $i$

The set of states is $\{s \subseteq V \mid s \vDash \theta\}$. Call $(\mathcal{F}, s)$ a scenario.

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## Symbolic Semantics

$\mathcal{F}, s \vDash K \varphi$ iff $s \cap O_{i}=s^{\prime} \cap O_{i}$ implies $\mathcal{F}, s^{\prime} \vDash \varphi$

## From Knowledge Structures to Kripke Models

## Theorem

For every knowledge structure there is an equivalent S5 Kripke Model and vice versa.

## Example

The knowledge structure

$$
\mathcal{F}=\left(V=\{p, q\}, \theta=p \vee q, O_{\text {Alice }}=\{p\}, O_{\text {Bob }}=\{q\}\right)
$$

is equivalent to this Kripke model:


## From Kripke Models to Knowledge Structures

(This is the tricky direction.)

## Example


is equivalent to this knowledge structure:

$$
\left(V=\left\{p, p_{2}\right\}, \theta=p_{2} \rightarrow p, O_{\text {Alice }}=\varnothing, O_{\text {Bob }}=\left\{p_{2}\right\}\right)
$$

with actual state: $\left\{p, p_{2}\right\}$

## Everything is boolean!

## Definition

Fix a knowledge structure $\mathcal{F}=\left(V, \theta, O_{1}, \cdots, O_{n}\right)$.
We define a local boolean translation $\|\cdot\|_{\mathcal{F}}$ :

- $\|p\|_{\mathcal{F}} \quad:=p$
- $\|\neg \varphi\|_{\mathcal{F}} \quad:=\neg\|\varphi\|_{\mathcal{F}}$
- $\left\|\varphi_{1} \wedge \varphi_{2}\right\|_{\mathcal{F}} \quad:=\left\|\varphi_{1}\right\|_{\mathcal{F}} \wedge\left\|\varphi_{2}\right\|_{\mathcal{F}}$
- $\left\|K_{i} \varphi\right\|_{\mathcal{F}} \quad:=\forall\left(V \backslash O_{i}\right)\left(\theta \rightarrow\|\varphi\|_{\mathcal{F}}\right)$
- \|[! $\varphi] \psi\left\|_{\mathcal{F}} \quad:=\right\| \varphi\left\|_{\mathcal{F}} \rightarrow\right\| \psi \|_{\mathcal{F}^{\varphi}}$


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## Theorem

For all scenarios $(\mathcal{F}, s)$ and all formulas $\varphi$ :
$\mathcal{F}, s \vDash \varphi \Longleftrightarrow s \vDash\|\varphi\|_{\mathcal{F}}$

## Example: Symbolic Muddy Children I

$$
\mathcal{F}_{0}=\left(\begin{array}{ll} 
& O_{1}=\left\{p_{2}, p_{3}\right\} \\
V=\left\{p_{1}, p_{2}, p_{3}\right\}, \theta_{0}=\top, & O_{2}=\left\{p_{1}, p_{3}\right\} \\
& O_{3}=\left\{p_{1}, p_{2}\right\}
\end{array}\right)
$$

"At least one of you is muddy."

## Example: Symbolic Muddy Children I

$$
\mathcal{F}_{0}=\left(\begin{array}{ll} 
& O_{1}=\left\{p_{2}, p_{3}\right\} \\
V=\left\{p_{1}, p_{2}, p_{3}\right\}, \theta_{0}=\mathrm{T}, & O_{2}=\left\{p_{1}, p_{3}\right\} \\
& O_{3}=\left\{p_{1}, p_{2}\right\}
\end{array}\right)
$$

"At least one of you is muddy."

$$
\mathcal{F}_{1}=\left(\begin{array}{ll} 
& O_{1}=\left\{p_{2}, p_{3}\right\} \\
V=\left\{p_{1}, p_{2}, p_{3}\right\}, \theta_{1}=\left(p_{1} \vee p_{2} \vee p_{3}\right), & O_{2}=\left\{p_{1}, p_{3}\right\} \\
& O_{3}=\left\{p_{1}, p_{2}\right\}
\end{array}\right)
$$

## Example: Symbolic Muddy Children I

$$
\mathcal{F}_{0}=\left(\begin{array}{l}
O_{1}=\left\{p_{2}, p_{3}\right\} \\
V=\left\{p_{1}, p_{2}, p_{3}\right\}, \theta_{0}=\top, \\
O_{2}=\left\{p_{1}, p_{3}\right\} \\
O_{3}=\left\{p_{1}, p_{2}\right\}
\end{array}\right)
$$

"At least one of you is muddy."

$$
\mathcal{F}_{1}=\left(\begin{array}{ll}
V=\left\{p_{1}, p_{2}, p_{3}\right\}, \theta_{1}=\left(p_{1} \vee p_{2} \vee p_{3}\right), & O_{1}=\left\{p_{2}, p_{3}\right\} \\
& O_{2}=\left\{p_{1}, p_{3}\right\} \\
O_{3}=\left\{p_{1}, p_{2}\right\}
\end{array}\right)
$$

"Do you know if you are muddy?" ... Nobody reacts.
This announcement is equivalent to:

$$
\left\|\bigwedge_{i \in I}\left(\neg\left(K_{i} p_{i} \vee K_{i} \neg p_{i}\right)\right)\right\|_{\mathcal{F}_{1}}=\left(p_{2} \vee p_{3}\right) \wedge\left(p_{1} \vee p_{3}\right) \wedge\left(p_{1} \vee p_{2}\right)
$$

Magic from 1986: Binary Decision Diagrams

(Read the classic Bryant 1986 for more details.)

## BDD Magic I

How long do you need to compare these two formulas?

$$
p_{3} \vee \neg\left(p_{1} \rightarrow p_{2}\right) \equiv \neg\left(p_{1} \wedge \neg p_{2}\right) \rightarrow p_{3}
$$

## BDD Magic I

How long do you need to compare these two formulas?

$$
p_{3} \vee \neg\left(p_{1} \rightarrow p_{2}\right) \equiv \neg\left(p_{1} \wedge \neg p_{2}\right) \rightarrow p_{3}
$$

Here are is their BDDs:


## BDD Magic II

This was not an accident, BDDs are canonical.
Theorem:

$$
\varphi \equiv \psi \quad \Longleftrightarrow \quad \operatorname{BDD}(\varphi)=\operatorname{BDD}(\psi)
$$

Equivalence checks are free and we have fast algorithms to compute $\operatorname{BDD}(\neg \varphi), \operatorname{BDD}(\varphi \wedge \psi), \operatorname{BDD}(\varphi \rightarrow \psi)$ etc.

## Results

Why translate DEL to boolean formulas?
Because computers are incredibly good at dealing with them!

| n | DEMO-S5 | SMCDEL |
| :---: | ---: | ---: |
| 6 | 0.012 | 0.002 |
| 8 | 0.273 | 0.004 |
| 10 | 8.424 | 0.008 |
| 11 | 46.530 | 0.011 |
| 12 | 228.055 | 0.015 |
| 13 | 1215.474 | 0.019 |
| 20 |  | 0.078 |
| 40 |  | 0.777 |
| 60 |  | 2.563 |

## So far, so good ...

This was S5 PAL, what about:

1. Non-S5 relations for belief?
2. Action Models with factual change?

## Motivating Example: Sally-Anne



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To model this we need non-S5 action models with factual change!

## Extension to non-S5

- $O_{i} \subseteq P$ always defines equivalence relations!
- How can we describe other relations?


## Extension to non-S5

- $O_{i} \subseteq P$ always defines equivalence relations!
- How can we describe other relations?
- Copy $P$ to describe reachability (Gorogiannis and Ryan 2002)
- Fresh variables $V^{\prime}:=\left\{p^{\prime} \mid p \in V\right\}$ and formulas $\mathcal{L}\left(V \cup V^{\prime}\right)$
- Actually: use BDD of boolean formula describing the relation


## Extension to non-S5: From relations to BDDs



## Extension to non-S5: Belief Structures

$\mathcal{F}=\left(V, \theta, \Omega_{1}, \cdots, \Omega_{n}\right)$ where

- V
- $\theta$
- $\Omega_{i} \in \mathcal{L}\left(V \cup V^{\prime}\right)$

Vocabulary
State Law
Observables
propositional variables boolean formula over $V$
encoded relation for $i$

The equivalent Kripke model is given by:

$$
R_{i} x y: \Longleftrightarrow\left(x \cup y^{\prime}\right) \vDash \Omega_{i}
$$

New translation for modalities:

$$
\left\|\square_{i} \psi\right\|_{\mathcal{F}}:=\forall V^{\prime}\left(\theta^{\prime} \rightarrow\left(\Omega_{i} \rightarrow\left(\|\varphi\|_{\mathcal{F}}\right)^{\prime}\right)\right)
$$

## The return of the postcondition

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## Transformers

## Definition

A transformer for $V$ is a tuple $\mathcal{X}=\left(V^{+}, \theta^{+}, V_{-}, \theta_{-}, \Omega^{+}\right)$where

- $V^{+}$is a set of fresh atomic propositions s.t. $V \cap V^{+}=\varnothing$
- $\theta^{+}$is a possibly epistemic formula from $\mathcal{L}\left(V \cup V^{+}\right)$
- $V_{-} \subseteq V$ is the modified subset of the original vocabulary
- $\theta_{-}: V_{-} \rightarrow \mathcal{L}_{B}\left(V \cup V^{+}\right)$encodes postconditions
- $\Omega_{i}^{+} \in \mathcal{L}_{B}\left(V^{+} \cup V^{+\prime}\right)$ describe observations for each $i$
to transform $\mathcal{F}=\left(V, \theta, \Omega_{i}\right)$, let $\mathcal{F} \times \mathcal{X}:=\left(V^{\text {new }}, \theta^{\text {new }}, \Omega_{i}^{\text {new }}\right)$ where

1. $V^{\text {new }}:=V \cup V^{+} \cup V_{-}^{\circ}$
2. $\theta^{\text {new }}:=$

$$
\left[V_{-} / V_{-}^{\circ}\right]\left(\theta \wedge\left\|\theta^{+}\right\|_{\mathcal{F}}\right) \wedge \wedge_{q \in V^{-}}\left(q \leftrightarrow\left[V_{-} / V_{-}^{\circ}\right]\left(\theta_{-}(q)\right)\right)
$$

3. $\Omega_{i}^{\text {new }}:=\left(\left[V_{-} / V_{-}^{\circ}\right]\left[\left(V_{-}\right)^{\prime} /\left(V_{-}^{\circ}\right)^{\prime}\right] \Omega_{i}\right) \wedge \Omega_{i}^{+}$

## Simple Example: Coin Flip hidden from a



$$
\begin{array}{llll} 
& (V=\{p\}, & \theta=p, & \Omega_{a}=\top, \\
\times & \left(V_{b}=\top\right) \\
V_{-}=\{q\}, & \theta^{+}=\top, & \Omega_{a}^{+}=\top, & \left.\Omega_{b}^{+}=q \leftrightarrow q^{\prime}\right) \\
=\left(V=\left\{p, q, p^{\circ}\right\}\right. & \theta=p^{\circ} \wedge(p \leftrightarrow q), & \Omega_{a}=\top & \left.\Omega_{b}=q \leftrightarrow q^{\prime}\right)
\end{array}
$$

## Monster Example: Symbolic Sally-Anne I

- Sally is in the room: $p$, Marble is in the box: $t$
- Question after the actions: Does Sally believe that the marble is in the box: $\square_{s} t$ ?


## Monster Example: Symbolic Sally-Anne I

- Sally is in the room: $p$, Marble is in the box: $t$
- Question after the actions: Does Sally believe that the marble is in the box: $\square_{s} t$ ?

Initial structure: $((\{p, t\},(p \wedge \neg t), \top, \top), p)$
$\mathcal{X}_{1}$ : Sally puts the marble in the basket:

$$
\left(\left(\varnothing, \top,\{t\}, \theta_{-}(t)=\top, \top, \top\right), \varnothing\right) .
$$

$\mathcal{X}_{2}$ : Sally leaves: $\left(\left(\varnothing, \top,\{p\}, \theta_{-}(p)=\perp, \top, \top\right), \varnothing\right)$.
$\mathcal{X}_{3}$ : Anne puts the marble in the box, not observed by Sally:

$$
\left(\left(\{q\}, \top,\{t\}, \theta_{-}(t)=(\neg q \rightarrow t) \wedge(q \rightarrow \perp), \neg q^{\prime}, q \leftrightarrow q^{\prime}\right),\{q\}\right)
$$

$\mathcal{X}_{4}$ : Sally comes back: $\left(\left(\varnothing, \top,\{p\}, \theta_{-}(p)=\top, \top, \top\right), \varnothing\right)$.

The slide we will skip

$$
\begin{array}{ll} 
& ((\{p, t\},(p \wedge \neg t), \top, \top), p) \\
\times & \left(\left(\varnothing, \top,\{t\}, \theta_{-}(t)=\top, \top, \top\right), \varnothing\right) \\
=\quad & \left(\left(\left\{p, t, t^{\circ}\right\},\left(p \wedge \neg t^{\circ}\right) \wedge t, \top, \top\right),\{p, t\}\right) \\
\times & \left(\left(\varnothing, \top,\{p\}, \theta_{-}(p)=\perp, \top, \top\right), \varnothing\right) \\
= & \left(\left(\left\{p, t, t^{\circ}, p^{\circ}\right\},\left(p^{\circ} \wedge \neg t^{\circ}\right) \wedge t \wedge \neg p, \top, \top\right),\left\{t, p^{\circ}\right\}\right) \\
\equiv \vee & ((\{p, t\}, t \wedge \neg p, \top, \top),\{t\}) \\
\times \quad & \left(\left(\{q\}, \top,\{t\}, \theta_{-}(t)=(\neg q \rightarrow t) \wedge(q \rightarrow \perp), \neg q^{\prime}, q \leftrightarrow q^{\prime}\right),\{q\}\right) \\
= & \left(\left(\left\{p, t, q, t^{\circ}\right\}, t^{\circ} \wedge \neg p \wedge\left(t \leftrightarrow\left(\left(\neg q \rightarrow t^{\circ}\right) \wedge(q \rightarrow \perp)\right)\right), \neg q^{\prime}, q \leftrightarrow q^{\prime}\right),\{q\}\right. \\
= & \left(\left(\left\{p, t, q, t^{\circ}\right\}, t^{\circ} \wedge \neg p \wedge(t \leftrightarrow \neg q), \neg q^{\prime}, q \leftrightarrow q^{\prime}\right),\{q\}\right) \\
\equiv v & \left(\left(\{p, t, q\}, \neg p \wedge(t \leftrightarrow \neg q), \neg q^{\prime}, q \leftrightarrow q^{\prime}\right),\{q\}\right) \\
\times & \left(\left(\varnothing, \top,\{p\}, \theta_{-}(p)=\top, \top, \top\right), \varnothing\right) \\
= & \left(\left(\left\{p, t, q, p^{\circ}\right\}, \neg p^{\circ} \wedge(t \leftrightarrow \neg q) \wedge p, \neg q^{\prime}, q \leftrightarrow q^{\prime}\right),\{p, q\}\right) \\
\equiv v & \left(\left(\{p, t, q\},(t \leftrightarrow \neg \neg) \wedge p, \neg q^{\prime}, q \leftrightarrow q^{\prime}\right),\{p, q\}\right)
\end{array}
$$

Everything on the previous scary slide are boolean operations, so we blindly trust a computer to deal with it.


## Monster Example: Symbolic Sally-Anne IIII

In the last scene Sally believes the marble is in the basket:

$$
\begin{array}{ll} 
& \{p, q\} \vDash \square_{s t} \\
\Longleftrightarrow & \{p, q\} \vDash \forall V^{\prime}\left(\theta^{\prime} \rightarrow\left(\Omega_{\mathrm{s}} \rightarrow t^{\prime}\right)\right) \\
\Longleftrightarrow & \{p, q\} \vDash \forall\left\{p^{\prime}, t^{\prime}, q^{\prime}\right\}\left(\left(t^{\prime} \leftrightarrow \neg q^{\prime}\right) \wedge p^{\prime} \rightarrow\left(\neg q^{\prime} \rightarrow t^{\prime}\right)\right) \\
\Longleftrightarrow & \{p, q\} \vDash T
\end{array}
$$


(François Schwarzentruber: Hintikka's world)

## Summary

- representation matters!
- symbolic model checking DEL gives a big speed-up
- knowledge/belief structures encode Kripke models
- transformers provide a modular approach for ontic and epistemic actions


## Future Work

- Comparison with (Charrier and Schwarzentruber 2017)
- Find big examples and benchmark!
- Limit postconditions to $T$ and $\perp$ ?
github.com/jrclogic/SMCDEL


## Bonus Slide: Comparison with Mental Programs / Succinct DEL

Similar approach in (Charrier and Schwarzentruber 2017). Mental programs describe which change is allowed: $q \mapsto T, p \mapsto q, \ldots$

- Observational BDDs and mental programs are dual in memory consumption:

| Relation | BDD | Mental Program |
| :--- | :--- | :--- |
| Identity | $2 \cdot\|V\|$ | 1 |
| Total | 1 | $2 \cdot\|V\|$ |

## References

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